

On the Exact Solution of the No-Wait Flow Shop Problem with Due Date Constraints

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Abstract

This paper deals with the no-wait flow shop scheduling problem with due date constraints. In the no-wait flow shop problem, waiting time is not allowed between successive operations of jobs. Moreover, the jobs should be completed before their respective due dates; due date constraints are dealt with as hard constraints. The considered performance criterion is makespan. The problem is strongly NP-hard. This paper develops a number of distinct mathematical models for the problem based on different decision variables. Namely, a mixed integer programming model, three quadratic mixed integer programming models, and two constraint programming models are developed. Moreover, a novel modelling approach is developed for the problem. This new modeling technique facilitates the investigation of some of the important characteristics of the problem; this results in a number of propositions to rule out a large number of infeasible solutions from the set of all possible permutations. Afterward, the new modelling technique and the resulting propositions are incorporated into a new exact algorithm to solve the problem to optimality. To investigate the performance of the mathematical models and to compare them with the developed exact algorithm, a number of test problems are solved and the results are reported. Computational results demonstrate that the developed algorithm is significantly faster than the mathematical models.

Keywords: No-Wait Flow Shop; Due Date Constraints; Mixed Integer Programming; Constraint Programming; Enumeration Algorithm

1. Introduction

In the no-wait flow shop problem, a special case of the classical flow shop problem, no waiting time is allowed between successive operations of jobs. In other words, once processing of a certain job is started, no interruption is permitted between operations of the job. In this paper, completion of each job is associated with a due date, i.e., jobs must be completed before their due dates. Due date side-constraints are among the most applicable constraints in scheduling and sequencing literature because real-world jobs are usually accompanied by a deadline for completion (Hunsucker and Shah 1992). In this paper, it is assumed that all the jobs are ready at time zero (all release dates are zero) and the considered performance measure is makespan. According to the three-field notation of the scheduling problems (Graham et al. 1979), the problem can be designated as $F | nwt, d_j | C_{\max}$.

King and Spachis (1980) proved that the no-wait flow shop problem with makespan performance measure ($F | nwt | C_{\max}$) can be transformed to the Asymmetric Travelling Salesperson Problem (ATSP). Röck (1984) proved that ($F | nwt | C_{\max}$) is NP-hard. Since $F | nwt, d_j | C_{\max}$ is a harder problem than $F | nwt | C_{\max}$, it can be inferred that $F | nwt, d_j | C_{\max}$ is also NP-hard.

Industrial applications mentioned in the literature for $F | nwt, d_j | C_{\max}$ include chemical industries (Rajendran 1994), food industries (Hall and Sriskandarajah 1996), steel production (Wismer 1972), pharmaceutical industries (Raaymakers and Hoogeveen 2000), and production of concrete products (Grabowski and Pempera 2000). Hall and Sriskandarajah (1996) provide a comprehensive review of the applications of the problem.

The reputation of a company as a reliable firm will tremendously damage if it frequently delivers jobs after their due dates are passed (even if the number of late days is relatively small). Moreover, trust between companies will be damaged if late jobs are not frequent, but a few jobs are delivered considerably past their due dates. Note that on-time delivery of the jobs can be only one of the goals of a company. Companies can be interested in optimizing other criteria such as makespan, while avoiding late days or tardy jobs. Hence, $F | nwt, d_j | C_{\max}$ is not only an applicable problem with many real-world applications, but it is proved to be NP-hard.

The literature is rich with studies that develop heuristic or metaheuristic methods in order to deal with no-wait flow shop problems with or without due date constraints. For the case of $F | nwt, d_j | \gamma$, due date constraints have been traditionally considered as soft constraints. In other words, violating due date constraints has been permitted with the objective function of minimizing a measure of the tardiness (e.g., number of tardy jobs or number of late days). Tardiness measures have frequently been combined with other performance measures such as makespan, total flow time, etc.; however, due date constraints have rarely been studied as hard constraints. This is mainly due to the fact that generating a feasible solution for the problem, or proving that a feasible solution does not exist, turns into a very challenging task, especially when due dates are not too loose or too tight. Since no-wait flow shop problem with due date constraints is strongly NP-hard, several algorithms have been devised to deal with the problem (Rajasekera et al. 1991, Hunsucker and Shah 1992, Sarper 1995, Brah 1996, Gupta et al. 2000, Gowrishankar et al. 2001, Kaminsky and Lee 2002, Błażewicz et al. 2005, Błażewicz et al. 2008, Hasanzadeh et al. 2009, Dhingra and Chandna 2010, Tang et al. 2011, Panwalkar and Koulamas 2012, Ebrahimi et al. 2013, Tari and Olfat 2013, Samarghandi Article in Press). All of these methods first relax the due date constraints and then solve the no-wait scheduling problem with a variant of lateness measure in the objective function by means of a metaheuristic or a heuristic algorithm.

On the other hand, mathematical programming techniques have long been employed to solve sequencing and scheduling problems. Selen and Hott (1986) developed a mixed integer programming for a flow shop system with more than one machine. Stafford (1988) developed a mixed integer linear

programming (MILP) based on the all-integer model of Wagner (1959). Tseng et al. (2004) performed an empirical study to evaluate the performance of the different mixed integer programming (MIP) models for permutation flow shop problems; results of this study were in line with the results of Pan (1997) for the case of regular job shop and flow shop problems. Pan (1997) reported the models of Manne (1960), Wagner (1959), and Wilson (1989) as the first, second, and third best MILP formulations respectively; models developed by Bowman (1959), Gupta (1971), Morton and Pentico (2010), Baker and Baker (1974), and Stafford (1988) come next. It should be noted that these models are not reported in any special order.

Pan and Chen (2005) developed a mixed binary integer programming (MBIP) model for reentrant job shop scheduling problem. Ziaee and Sadjadi (2007) developed seven MBIP formulations for the flow shop sequencing problem and considered different constraints such as due dates, ready times, etc., and studied makespan, weighted mean flow time, and weighted mean tardiness as their performance measures. Javadi et al. (2008) developed a linear programming model for the no-wait flow shop problem with fuzzy objective functions. Ramezani et al. (2010) developed a mathematical programming model to minimize the earliness and tardiness costs in a flow shop context, where processing times can be zero.

This study develops a number of mathematical programming formulations for $F | nwt, d_j | C_{\max}$. More specifically, an MIP, three quadratic MIPs, and two constraint programming (CP) models are developed. Due date constraints are dealt with as hard constraints. Baker and Keller (2010) report that for the case of single machine sequencing problems mathematical programming models can be employed to optimally solve instances with as many as 50 jobs. However, computational experiments in this paper reveal that the number of jobs in $F | nwt, d_j | C_{\max}$ instances should be significantly smaller so that the problem can be solved to optimality using mathematical models.

In addition, this paper considers a new modelling approach for the no-wait flow shop problem and proves a number of theorems based on the characteristics of the $F | nwt, d_j | C_{\max}$. Afterward, an enumeration algorithm is proposed to solve $F | nwt, d_j | C_{\max}$ to optimality; this algorithm employs the results of the proven propositions to restrict the feasible region of the problem and accelerate the search speed. Computational results reveal that the proposed algorithm is significantly faster than the discussed mathematical models.

The rest of the paper is organized as follows. Section 2 describes the notations used. Section 3 formulates the mathematical programming models. Section 4 describes the novel modelling approach and the enumeration algorithm. Computational experiments are reported in section 5. Section 6 gives concluding remarks and discusses future research directions.

2. Problem Description

In the considered $F | nwt, d_j | C_{\max}$ it is assumed that: 1) all jobs follow the same predefined order of operations; 2) no preemption or interruption is allowed; 3) no job can be processed by more than one machine at the same time, and no machine can process more than one operation at the same time; 4) all jobs must visit all machines, possibly with zero processing time on some of the machines; and 5) there should be no waiting time between consecutive operations of a job. The following notation is used throughout the rest of this paper:

m	Number of machines
n	Number of jobs
J_j	Job j
p_{ij}	Processing time of i th operation of J_j
c_{jk}	Contribution of J_k to the objective function when placed immediately after J_j
S_{ij}	Starting time of i th operation of J_j
F_j	Finish time of J_j
d_j	Due date of J_j

A solution of $F | nwt | C_{\max}$ can be described with a sequence $\pi = (\pi_1, \pi_2, \dots, \pi_n)$ of n jobs. It should be noted that $F | nwt | C_{\max}$ is a permutation scheduling, i.e. the sequence of the jobs on all machines is the same. Hence, the contribution of job k when placed immediately after job j (c_{jk}) is not dependent to the machines. Contribution of J_j to C_{\max} when J_j is the first scheduled job in a sequence is calculated as follows:

$$c_{0j} = \sum_{i=1}^m p_{ij}; j = 1, 2, \dots, n \quad (1)$$

The algorithm of Samarghandi (Article in Press) can be employed with small modifications to calculate $c_{jk}; j, k = 1, 2, \dots, n; k \neq j$. Note that $c_{jj} = 0; j = 1, 2, \dots, n$.

Step 1: Define a counter for the operations of π_j and a counter for operations of $\pi_k = \pi_{j+1}$; call the former counter t and the latter w .

Step 2: Set $t = 2; w = 1$.

Step 3: If $p_{ij} \geq p_{wk}$, set $t \leftarrow t + 1$ and $w \leftarrow w + 1$. If $t = m + 1$, proceed to step 8; otherwise go back to the beginning of step 3. If $p_{ij} < p_{wk}$, proceed to step 4.

Step 4: Set $z = \left\{ \min h \mid \left(\sum_{l=t}^h p_{lj} \right) - p_{wk} \geq 0 \right\}$ and proceed to step 5. If the value of z cannot be determined, go to step 7.

Step 5: Set $p_{zj} \leftarrow \left(\sum_{l=t}^z p_{lj} \right) - p_{wk}$. Proceed to the next step.

Step 6: Set $w \leftarrow w + 1$ and $t \leftarrow z$. If $t = m + 1$, go to step 8; otherwise, go back to step 3.

Step 7: Set $c_{jk} \leftarrow \left(\sum_{l=w}^m p_{lk} \right) - \left(\sum_{l=t}^m p_{lj} \right)$. Stop.

Step 8: Set $c_{jk} = p_{mk}$. Stop.

The contribution matrix C is an $(n+1) \times n$ matrix that lists the contribution of each job to the makespan if placed after a certain job in the sequence.

$$C = [c_{jk}; j = 0, 1, \dots, n; k = 1, 2, \dots, n] = \begin{bmatrix} c_{01} & \cdots & c_{0n} \\ \vdots & \ddots & \vdots \\ c_{n1} & \cdots & c_{nn} \end{bmatrix} \quad (2)$$

The first row of C can be computed using (1). To calculate the rest of this matrix, the above algorithm should be used. Moreover, $c_{jj} = 0; j = 1, 2, \dots, n$.

3. The Developed Models

This section presents the developed mathematical models.

3.1 Model I

The first model is based on the developed model of Samarghandi (Article in Press) and employs the decision variable defined by (3). This model works directly with the problem data and does not require the algorithm of section 2 to calculate the contribution matrix.

$$x_{jk} = \begin{cases} 1 & \text{if } J_k \text{ is placed immediately after } J_j \text{ in the sequence} \\ 0 & \text{Otherwise} \end{cases} \quad (3)$$

The model, which is a mixed integer programming, is as follows:

$$\text{minimize } C_{\max} \quad (4)$$

$$C_{\max} \geq S_{mj} + p_{mj}; \quad j = 1, 2, \dots, n \quad (5)$$

$$S_{ik} + M(1 - x_{jk}) \geq S_{ij} + p_{ij}; \quad i = 1, 2, \dots, m; \quad j, k = 1, 2, \dots, n \quad (6)$$

$$S_{(i+1)j} = S_{ij} + p_{ij}; \quad i = 1, 2, \dots, m-1; \quad j = 1, 2, \dots, n \quad (7)$$

$$S_{mj} + p_{mj} \leq d_j; \quad j = 1, 2, \dots, n \quad (8)$$

$$\sum_{j=1}^n x_{jk} \leq 1; \quad k = 1, 2, \dots, n \quad (9)$$

$$\sum_{k=1}^n x_{jk} \leq 1; \quad j = 1, 2, \dots, n \quad (10)$$

$$x_{jk} + x_{kj} \leq 1; \quad j, k = 1, 2, \dots, n \quad (11)$$

$$\sum_{j=1}^n \sum_{k=1}^n x_{jk} = n - 1 \quad (12)$$

$$S_{ij} \geq 0; \quad i = 1, 2, \dots, m; \quad j = 1, 2, \dots, n \quad (13)$$

$$x_{jk} \in \{0, 1\}; \quad j, k = 1, 2, \dots, n \quad (14)$$

In this model, the objective function is to minimize the makespan; M is a sufficiently large number. (5) defines that makespan equals the finish time of the last operation of the last job. (6) assures that the operations do not overlap; this constraint is binding if J_k is scheduled immediately after J_j in the sequence. (7) imposes the no-wait constraints. (8) represents the due date constraint; according to (8), the last operation of each job should finish before its associated due date. Constraints (9), (10), (11), and (12) guarantee that all the jobs will appear exactly once in the sequence.

3.2 Model II

The sequence π is modified to include two dummy jobs, π_0 and π_{n+1} with zero processing times. Contribution matrix C of equation (2) is modified to C' to confirm that π_0 and π_{n+1} will be located in the first and the last positions in the sequence accordingly. In this matrix, $c_{jj} = 0; j = 1, 2, \dots, n$.

$$C'_{(n+2) \times (n+2)} = [c_{jk}; j, k = 0, 1, \dots, n+1] = \begin{bmatrix} 0 & c_{01} & \cdots & c_{0n} & 0 \\ 0 & \vdots & \ddots & \vdots & 0 \\ 0 & c_{n1} & \cdots & c_{nm} & 0 \\ M & 0 & \cdots & 0 & 0 \end{bmatrix} \quad (15)$$

$x_{jk}; j, k = 0, 1, \dots, n+1$ is the binary decision variable of the model; $x_{jk} = 1$ indicates that J_k is placed immediately after J_j . If $x_{0k} = 1$, then J_k is the first job in the sequence. Accordingly, the following model is formulated.

$$\text{minimize } \sum_{j=0}^{n+1} \sum_{k=0}^{n+1} c_{jk} x_{jk} \quad (16)$$

$$\sum_{j=0}^n x_{jk} = 1; \quad k = 1, 2, \dots, n+1 \quad (17)$$

$$\sum_{k=1}^{n+1} x_{jk} = 1; \quad j = 0, 1, \dots, n \quad (18)$$

$$x_{j0} = 0; \quad j = 0, 1, \dots, n+1 \quad (19)$$

$$x_{(n+1)k} = 0; \quad k = 0, 1, 2, \dots, n+1 \quad (20)$$

$$u_0 = 1 \quad (21)$$

$$2 \leq u_j \leq n+2; \quad j = 1, 2, \dots, n+1 \quad (22)$$

$$u_j - u_k + 1 \leq (n+1)(1 - x_{jk}); \quad j, k = 1, 2, \dots, n+1; j \neq k \quad (23)$$

$$x_{jj} = 0; \quad j = 0, 1, 2, \dots, n+1 \quad (24)$$

$$F_0 = 0 \quad (25)$$

$$F_k = \sum_{j=0}^{n+1} (c_{jk} + F_j) x_{jk}; \quad k = 1, 2, \dots, n+1 \quad (26)$$

$$F_j \leq d_j; \quad j = 0, 1, 2, \dots, n+1 \quad (27)$$

$$x_{jk} \in \{0, 1\}; \quad j, k = 0, 1, \dots, n+1 \quad (28)$$

where (19) and (20) force the model to place the dummy jobs in their intended locations in the sequence. Equations (21), (22) and (23) are similar to the Miller-Tucker-Zemlin (MTZ) equations (Desrochers and Laporte 1991) and are used to avoid sub-tours when scheduling jobs in the sequence.

According to (24) no job can be placed after itself. The recursive quadratic equation (26) calculates the finish time of J_k based on its predecessors. Due date constraints are enforced by (27). The following equations can be used to extract the sequence from the decision variables once the model is solved:

$$\pi_1 = \sum_{k=1}^n kx_{0k}$$

$$\pi_j = \sum_{k=1}^n kx_{\pi_{(j-1),k}}; \quad j = 2, 3, \dots, n$$

3.3 Model III

Although this model employs the same contribution matrix as Model I and Model II, the decision variable of this model, is defined as follows (as there are n jobs and n possible locations in the sequence):

$$x_{lj} = \begin{cases} 1 & \text{if } \pi_l = J_j \\ 0 & \text{otherwise} \end{cases} \quad l, j = 1, 2, \dots, n \quad (29)$$

Based on this definition for the decision variable, the model can be formulated as:

$$\text{minimize } L_n \quad (30)$$

$$\sum_{l=1}^n x_{lj} = 1; \quad j = 1, 2, \dots, n \quad (31)$$

$$\sum_{j=1}^n x_{lj} = 1; \quad l = 1, 2, \dots, n \quad (32)$$

$$\sum_{l=1}^n \sum_{j=1}^n x_{lj} = n \quad (33)$$

$$L_1 = \sum_{j=1}^n c_{0j} x_{1j} \quad (34)$$

$$L_l = \sum_{j=1}^n \sum_{\substack{k=1 \\ k \neq j}}^n x_{(l-1)j} x_{lk} c_{jk} + L_{l-1}; \quad l = 2, 3, \dots, n \quad (35)$$

$$L_l \leq \sum_{j=1}^n d_j x_{lj}; \quad l = 1, 2, \dots, n \quad (36)$$

$$L_l \geq 0; \quad l = 1, 2, \dots, n \quad (37)$$

$$x_{lj} \in \{0,1\}; \quad l, j = 1, 2, \dots, n \quad (38)$$

where L_l is an intermediary variable, used to calculate the finish time of π_l . Thus, (30) minimizes the makespan by minimizing the finish time of π_n . (34) calculates the finish time of π_1 ; the first term of (35) calculates the contribution of J_k to the makespan when it is located after J_j . (36) is the due date constraint.

3.4 Model IV

Model III is formulated based on the finish time of the jobs in different positions; finish times were calculated by equations that were independent from the job that is located in each position. However, it is possible to modify Model III to calculate the finish times of the jobs rather than the finish times of the positions. In Model III, L_l is calculated by searching the rows of the C' matrix. In the modified model, finish time calculations are performed by exploring both the rows and the columns of C' . Assume that F_j is the finish time of J_j . Therefore, in Model IV equations (34) and (35) should be replaced with the following:

$$F_k = \begin{cases} x_{1j} c_{0j} & \text{if } x_{1j} c_{0j} > 0 \\ \sum_{l=2}^n \sum_{\substack{k=1 \\ k \neq j}}^n x_{(l-1)j} x_{lk} c_{jk} + \sum_{l=2}^n \sum_{\substack{k=1 \\ k \neq j}}^n x_{(l-1)j} x_{lk} F_j & \text{otherwise} \end{cases} \quad (39)$$

The first condition of (39) is true only for π_1 . All the other jobs will utilize the second condition. Finish time of J_k depends on the finish time of its immediate predecessor J_j . Once the finish times are defined by (39), the objective function of Model III and the due date constraints will be modified accordingly:

$$\text{minimize } \max_j F_j$$

$$F_j \leq d_j; \quad j = 1, 2, \dots, n$$

In the modified model equations (34) and (35) should be replaced with (39), which is a quadratic non-convex equation. This makes the model complicated and difficult to solve. Therefore, although the model is of theoretical interest, it will not be further investigated for the computational experiments.

3.5 Model V

Unlike previous models, Model V and Model VI are formulated based on the special characteristics and properties of constraint programming (CP). The decision variable that will be used for Model V and Model VI is defined as $x_l = j$ if J_j is placed in location l ; one should define $x_0 = 0$. The contribution of the jobs to the makespan is defined the same way as in the previous models, which is based on placing a certain job after another job; however, for Model V and Model VI it is assumed that $c_{jj} = M$; $j = 1, 2, \dots, n$ (M is a sufficiently large number). This will prevent the CP model from placing a certain job after itself. Accordingly, the first CP model will be as follows:

$$\text{minimize } c_{0,x_1} + \sum_{l=2}^n c_{x_{l-1},x_l} \quad (40)$$

$$\text{All Different}(x_1, x_2, \dots, x_n) \quad (41)$$

$$\sum_{l=1}^j c_{x_{(l-1)},x_l} \leq d_{x_j}; \quad j = 1, 2, \dots, n \quad (42)$$

$$x_l \in \{1, 2, \dots, n\}; \quad l = 1, 2, \dots, n \quad (43)$$

The objective function is defined based on the contribution of the jobs once the sequence is determined. The combination of (41) and (43) guarantees that all the jobs will be placed in the sequence, and each job will appear in the sequence only once. (42) is the due date constraint; finish times of the jobs are calculated based on the contribution of the previous jobs in the sequence.

3.6 Model VI

This model is based on the same decision variable as Model V. However, Model VI unlike Model V, works directly with the problem data and therefore, does not require the contribution matrix.

$$\text{minimize } S_{m,x_n} + p_{m,x_n} \quad (44)$$

$$\text{All Different}(x_1, x_2, \dots, x_n) \quad (45)$$

$$S_{i,x_{(j+1)}} \geq S_{i,x_j} + p_{i,x_j}; \quad i = 1, 2, \dots, m; \quad j = 1, 2, \dots, n-1 \quad (46)$$

$$S_{(i+1),x_j} = S_{i,x_j} + p_{i,x_j}; \quad i = 1, 2, \dots, m-1; \quad j = 1, 2, \dots, n \quad (47)$$

$$S_{m,x_j} + p_{m,x_j} \leq d_{x_j}; \quad j = 1, 2, \dots, n \quad (48)$$

$$S_{ij} \geq 0; \quad i = 1, 2, \dots, m; \quad j = 1, 2, \dots, n \quad (49)$$

$$x_j \in \{1, 2, \dots, n\}; \quad j = 1, 2, \dots, n \quad (50)$$

In this model, (46) means that the jobs should not overlap. (47) represents the no-wait constraints and (48) belongs to the due date constraints. The enumeration algorithm will be presented in the next section.

4. Search Graph and the Enumeration Algorithm

Figure 1 describes a search graph that represents the $F | nwt, d_j | C_{\max}$:

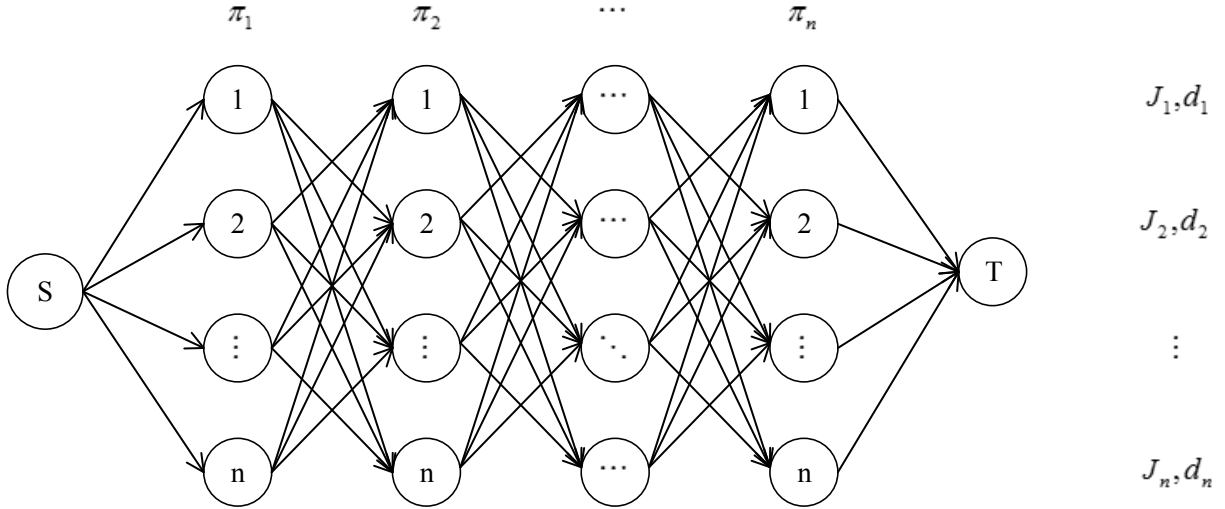


Figure 1 - The search graph representing $F | nwt, d_j | C_{\max}$

In this graph $G = \{V, E\}; |V| = n^2 + 2$; node which is located in the intersection of row $j; 1 \leq j \leq n$ and column $l; 1 \leq l \leq n$ represents job j if located in position l of permutation π ; S and T are dummy jobs with zero processing times, which represent the start and the finish of the flow shop system. G contains $n = |N|$ rows and columns. An arc exists between two nodes if and only if these nodes belong to two adjacent columns and they do not represent the same job; as a result, the number of arcs between two adjacent columns are $n(n-1)$ and the total number of arcs are $n(n-1)^2$. Arcs that start from node S or end at node T are exceptions and are not included in the above calculations. Figure 2 describes an instance of $F | nwt, d_j | C_{\max}$ with three jobs.

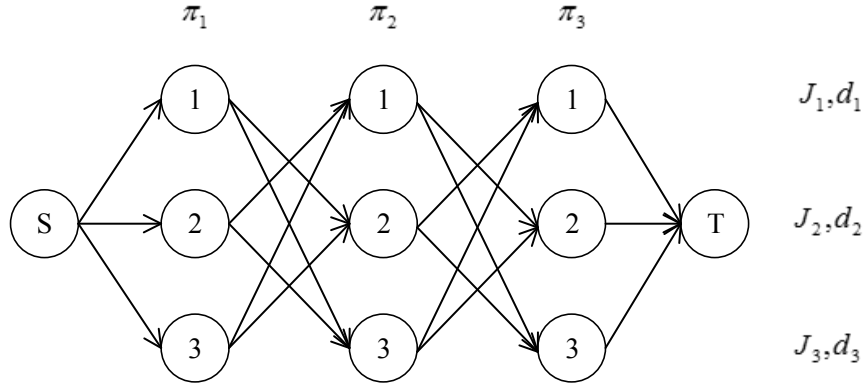


Figure 2 - An instance of $F | nwt, d_j | C_{\max}$

4.1 Definition of a Feasible Solution of $F | nwt | C_{\max}$ Based on the Graph Modelling

A feasible solution of $F | nwt | C_{\max}$ starts with S and ends with T ; it includes one and only one node in each row and in each column. As a result, Figure 3 characterizes the permutation $\pi = (2, 1, 3)$ and represents a feasible solution of $F | nwt | C_{\max}$ with three jobs.

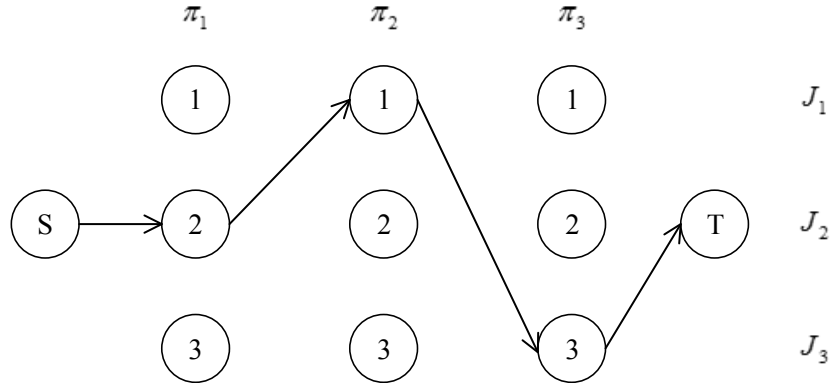


Figure 3 – A feasible solution of $F | nwt | C_{\max}$ with three jobs and three machines

Each arc $a_{jk}; 1 \leq j, k \leq n$, when a_{jk} exists, can be labeled with c_{jk} as defined by (2). a_{sj} represents the arc that connects S to J_j in column π_1 and is labeled with c_{0j} defined by (1). As a result, for Figure 3, the makespan is as follows:

$$C_{\max} = c_{02} + c_{21} + c_{13} \quad (51)$$

It can be noted that the permutation $\pi = (2, 1, 3)$ in Figure 3 is a feasible solution of $F | nwt, d_j | C_{\max}$ if:

$$\begin{aligned}
c_{02} &\leq d_2 \\
c_{02} + c_{21} &\leq d_1 \\
c_{02} + c_{21} + c_{13} &\leq d_3
\end{aligned} \tag{52}$$

Moreover, if $\pi = (2,1,3)$ is the shortest path from S to T , π is the optimum solution of the $F | nwt, d_j | C_{\max}$ instance which is described in Figure 3. It can be verified that the number of permutations for an instance of $F | nwt, d_j | C_{\max}$ with n jobs and m machines, as described by Figure 1, is $n!$.

Observation 1: suppose that LP_{j,π_l} represents the longest path from S to the node in the intersection of column π_l and row j . If $LP_{j,\pi_l} \leq d_j; \forall j \in \{1,2,\dots,n\}, \forall l \in \{1,2,\dots,n\}$, then the due date constraints can be removed and the problem reduces to $F | nwt | C_{\max}$.

Observation 2: if $LP_{j,\pi_n} \leq d_j; \forall j \in \{1,2,\dots,n\}$, then the due date constraints can be removed and the problem reduces to $F | nwt | C_{\max}$.

Observation 3: if $\exists j \in \{1,2,\dots,n\} | LP_{j,\pi_n} \leq d_j$, then the due date constraints for J_j can be removed from the problem.

Observation 4: suppose that SP_{j,π_l} represents the shortest path from S to the node in the intersection of column π_l and row j . If $\exists j \in \{1,2,\dots,n\} | SP_{j,\pi_l} > d_j, \forall l \in \{1,2,\dots,n\}$, then the problem is infeasible. If $\exists j \in \{1,2,\dots,n\} | SP_{j,\pi_l} > d_j, \forall l \in \{1,2,\dots,n\}$ or $\exists l \in \{1,2,\dots,n\} | SP_{j,\pi_l} > d_j, \forall j \in \{1,2,\dots,n\}$, then the problem is infeasible.

4.2 Eliminating Infeasible Solutions

In order to shrink the size of the set of solutions to enumerate to find the optimal solution, the following results are useful.

Observation 5: due to the no-wait constraints, any feasible solution of $F | nwt | C_{\max}$ with $p_{ij} > 0, \forall i, j$ is a permutation schedule, i.e. the order of jobs on all machines remains the same.

Observation 6: for $F | nwt | C_{\max}$, any non-semi-active feasible schedule can be easily transformed to a semi-active feasible schedule considering the no-wait constraint, with the same or a better objective

function value. This can be done by simply removing the non-necessary delays for all operations without changing the sequence or violating the no-wait constraints.

Observation 7: for any two consecutive jobs in a semi-active feasible solution of $F | nwt | C_{\max}$, there exists at least one machine with no idle time between processing of the operations of these two jobs, otherwise the solution would not be semi-active.

Proposition 1: for $F | nwt | C_{\max}$ with $p_{ij} > 0, \forall i, j$ with a non-empty feasible set, the set of semi-active feasible schedules and the set of active feasible schedules are non-empty and equal.

Proof: by Observation 6 it is clear that as long as the set of feasible solutions is not empty, then the set of all semi-active schedules is non-empty. Since the set of all active schedules is a subset of the set of all semi-active schedules, it is enough to prove that each semi-active schedule is also active. Due to the no-wait constraints and Observation 5 and Observation 7, it is impossible to construct a new schedule, through reordering the sequence, with at least one operation finishing earlier without delaying another operation. Hence any semi-active schedule is also active.

Corollary 1: there exists for $F | nwt | C_{\max}$ an optimal schedule that is active considering the no-wait constraints.

Proposition 2: for an active feasible solution of $F | nwt | C_{\max}$ with the partial permutation $(\dots, j, k, \dots, q, \dots)$, it can be proved that $c_{jk} < c_{jq} + c_{qk}$.

Proof: the proof is by contradiction. Assume that this is not true; then $c_{jk} \geq c_{jq} + c_{qk}$. Let C_{\max}^j be the objective function of the partial solution $\pi = (\dots, j)$; then $C_{\max}^j + c_{jk} \geq C_{\max}^j + c_{jq} + c_{qk}$. This means by scheduling job q between job j and job k the finish time of job k (F_k) must either remain the same or be reduced by some positive amount. In either case, none of the operations of job k will be delayed since there is no waiting time between the operations of a job. This means that one is able to schedule job q between job j and job k without delaying any of the operations of job k . This contradicts the assumption of the solution being active.

Corollary 2: given a partial permutation π for $F | nwt | C_{\max}$ with $F_j \leq d_j, \forall j \in \pi$, if constructing the partial permutation $\pi' = (\pi, k)$ for some k results in $F_k > d_k$, then any permutation of the form $\pi'' = (\dots, \pi, \dots, k, \dots)$, which places k after π , is infeasible.

Proof: finish time of each job is the sum of the contribution of the jobs in the partial sequence ending to that job. Therefore by Proposition 2, F_k will be increased by placing more jobs between π and job k . Among all permutations that place job k after π , the permutation (π, k, \dots) will have the smallest F_k which is still infeasible.

Observation 8: if $\exists l \in \{2, 3, \dots, n\}, j \in \{1, 2, \dots, n\} | SP_{j, \pi_l} > d_j$, then it is possible to remove this node as well as all of the arcs that start from or end at this node from G . In other words, by placing this job in location π_l of the permutation, the due date constraints will be violated. Removing a node in column π_1 means that the problem is infeasible; removing a node in column $\pi_l; 2 \leq l \leq n-1$ results in the removal of $2(n-1)$ arcs from G ; removing a node from column n results in the removal of n arcs from G .

4.3 The Enumeration Algorithm

Algorithm 1: the following algorithm represents the enumeration algorithm that solves $F | nwt, d_j | C_{\max}$ to optimality.

1. If $\exists j \in \{1, 2, \dots, n\} | SP_{j, \pi_1} > d_j$, stop. The problem is infeasible.
2. If $LP_{j, \pi_n} \leq d_j; \forall j \in \{1, 2, \dots, n\}$, remove the due date constraints to reduce the problem to $F | nwt | C_{\max}$.
3. Calculate $SP_{j, \pi_l}; l \in \{2, 3, \dots, n\}, j \in \{1, 2, \dots, n\}$. If $\exists j \in \{1, 2, \dots, n\} | SP_{j, \pi_l} > d_j; l \in \{2, 3, \dots, n\}$, remove the corresponding node and all of its arcs from the graph G ; call the remaining graph G' .
4. Find the shortest path between S and T with attention to the definition of the feasible solution of $F | nwt | C_{\max}$. If the found shortest path does not violate any of the due date constraints, it is optimal; compute the total contribution values of this path to calculate the makespan. Otherwise, proceed to step 5.
5. This step describes an enumeration sub-algorithm to solve G' to optimality. The objective of this sub-algorithm is to fathom all of the paths of the modified search graph (or G') from S to T until the optimum solution is found. The root node is S .
 - 5.1. Branch from S to all of the nodes in π_1 . Define l as the index for the positions in the permutation; in other words, l represents the current column in G' . Set $l \leftarrow 1$. Objective function value for node $j; j \in \{1, 2, \dots, n\}$ is $C_j^l = c_{0j}$. Fathom all nodes in G' for $l > 1$.

- 5.2.** Assume that $C_q^l = \max_j \{C_j^l \mid j = 1, 2, \dots, n; j \text{ is not selected or fathomed yet}\}$; update the current node to q ; break the ties by random selection, unfathom all the nodes in column $t \mid t > l$, and branch from q to all of its adjacent nodes in G' ; calculate $C_j^{l+1} \leftarrow C_q^l + c_{qj}; j \in \{1, 2, \dots, n \mid q \text{ and } j \text{ are adjacent}\}$.
- 5.3.** Fathom the nodes that violate the due date of their respective jobs in column $l+1$, and go to step 5.6 if $l \neq n-1$; otherwise proceed to step 5.4. Note that if due date constraints are violated when $l = 1$, according to step 1 the problem is infeasible.
- 5.4.** Compare $C_j^{l+1}; j \in \{1, 2, \dots, n\}$ with C_{\max}^{best} , the makespan of the best-known feasible solution (if the list of the complete feasible solutions is not empty); if $C_j^{l+1} > C_{\max}^{best}; j \in \{1, 2, \dots, n\}$, fathom node j in column $l+1$.
- 5.5.** If $l = n-1$ and there is at least one node in column $l+1$ which is not fathomed yet, then the paths to such nodes define different feasible solutions each with makespan which is at least as desirable as C_{\max}^{best} . Accordingly, compare the makespan of such nodes with each other and update C_{\max}^{best} with the best found makespan. Then, fathom all the nodes in column $l+1$ and proceed to 5.6.
- 5.6.** If all of the nodes in $l+1$ are fathomed, then fathom the current node and proceed to 5.6.1. Otherwise, set $l \leftarrow l+1$ and go to step 5.2.
- 5.6.1.** If there are nodes in the current column l , which have not yet been selected or fathomed during the course of the algorithm, do not change the value of l ; go to step 5.2. Otherwise proceed to 5.6.2.
- 5.6.2.** Set $l \leftarrow l-1$. If $l = 0$, stop. Report C_{\max}^{best} and its corresponding route as the optimum solution. If the list of the feasible solutions is empty, the problem is infeasible. Otherwise, restart step 5.6 from the beginning. ■

Figure 4 illustrates the enumeration sub-algorithm. Note that the above algorithm does not exploit the results of Corollary 2. In order to integrate Corollary 2 in the algorithm, steps 5.3 and 5.4 of Algorithm 1 should be modified as follows; this results in Algorithm 2. The rest of the steps remain unchanged.

Algorithm 2: modify steps 5.3 and 5.4 of Algorithm 1 as follows:

5.3.' Fathom all the nodes in column $l+1$; if $l \neq n-1$, then go to step 5.6. Otherwise, proceed to step 5.4'. Note that if due date constraints are violated when $l = 1$, according to step 1 of Algorithm 1 the problem is infeasible.

5.4.' Compare $C_j^{l+1}; j \in \{1, 2, \dots, n\}$ with C_{\max}^{best} , the makespan of the best-known feasible solution (if the list of the complete feasible solutions is not empty); if $C_j^{l+1} > C_{\max}^{best}; j \in \{1, 2, \dots, n\}$, fathom all the nodes in column $l + 1$. ■

Numerical results will be presented in the next section.

5. Computational Experiments

Conducting numerical experiments is an effective approach to compare the performance of the developed models. IBM ILOG CPLEX V12.6 was used to solve the developed mathematical models. Algorithms of Section 4 were coded by Microsoft Visual C++ 2013. All the numerical experiments were performed on a PC equipped with a 2GHz Intel Pentium IV CPU and 2 GB of RAM. To perform the computational analysis, a number of test problems generated by Samarghandi (Article in Press) were selected; namely, eight test problems for $F | nwt | C_{\max}$ accompanied with four different due date settings for each test problem. Moreover, six other test problems with larger instances for $F | nwt | C_{\max}$ were generated. Each test problem was then accompanied by four different due date settings. All the test problems were generated based on the same approach described by Samarghandi (Article in Press). Accordingly, a total of 56 test problems for $F | nwt, d_j | C_{\max}$ and 14 test problems for $F | nwt | C_{\max}$ were investigated in this paper; each distinct due date setting will be called a tightness factor and will be abbreviated as TF hereinafter. *Sam01* through *Sam08* are test problems for $F | nwt | C_{\max}$ from Samarghandi (Article in Press) and *Sam01+DD* through *Sam08+DD* are test problems with due date constraints from Samarghandi (Article in Press); problems generated in this study are *Sam09* through *Sam14* and *Sam09+DD* through *Sam14+DD*.

Best solutions of the models for the test problems will be reported at $T = 60$, $T = 300$, $T = 600$ and $T = 7200$ seconds. Before the results are presented, some of the complications when solving the problems will be discussed.

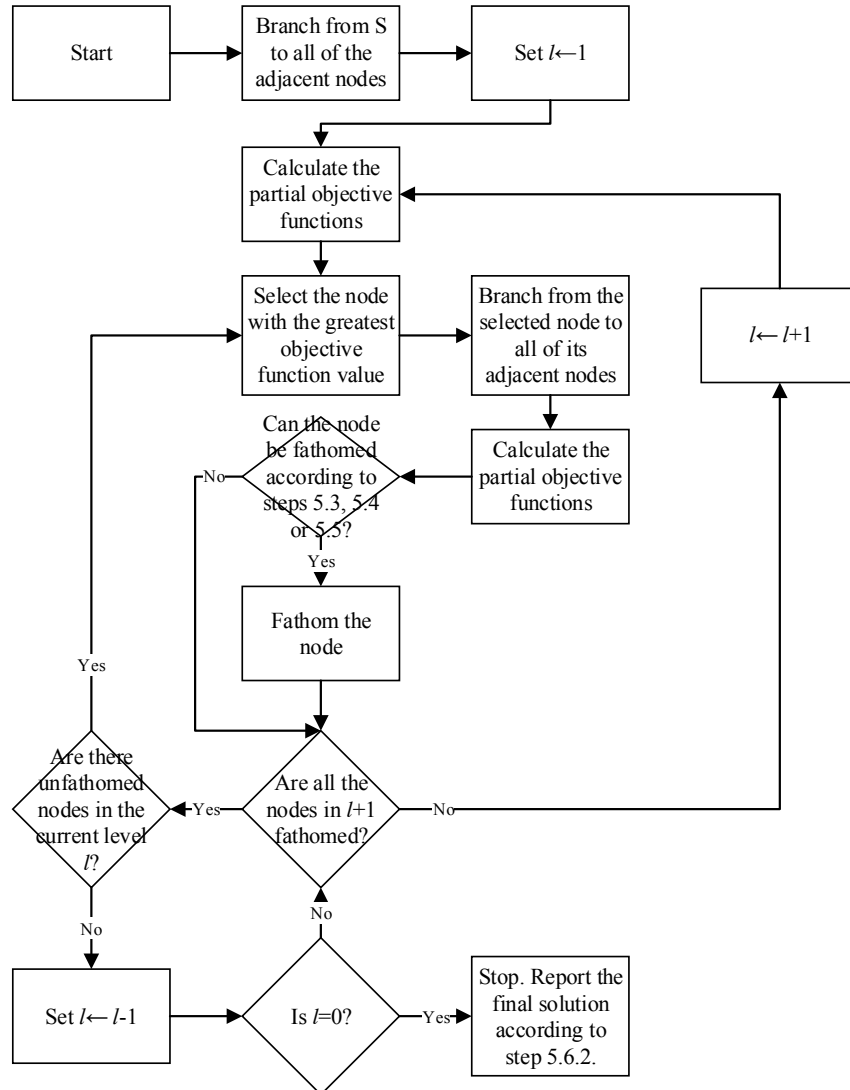


Figure 4 - Algorithm 1

5.1 Implementation Complications

Formulation of Model I is based on a very large number (M) in (6) that replicates either-or constraints. Although this is an effective method to prototype either-or constraints, the numerical value of M may result in complication in implementation of the model in any software package designed for solving mathematical modelling problems; IBM CPLEX is not an exception. If the value of M is not carefully chosen, CPLEX may eliminate M in the pre-solve phase. It is therefore recommended¹ that either-or constraints should be modelled by indicator constraints in order to eradicate the need for the numerical value of M . However, employing indicator constraints results in a reduction in the effectiveness

¹ <http://www-01.ibm.com/support/docview.wss?uid=swg21400084>

of the branching algorithm; this can result in an increase in the solution time. Numerical results of both of these approaches to implement Model I will be presented in section 5.2.

5.2 Numerical Results of the Developed Models

The equality (26) in Model II is a quadratic equation, which makes it a non-convex constraint. The same argument holds for equation (35) in Model III. Hence solving these two models even after relaxing the integrality constraint is not easy. There is a bulk of research on finding approximate solutions for non-convex binary integer programming using convex optimization techniques like SDP relaxation (see e.g. the pioneering paper of Goemans and Williamson (1995) on MAX-CUT Problem). However, this paper does not seek approximate solutions so the authors have taken this problem as an interesting future research direction. For this reason, in this paper Model II and Model III will not be included in the numerical experiments for $F | nwt, d_j | C_{\max}$.

On the other hand, in order to review the performance of Model II, the due date constraints of this model will be relaxed and computational experiments will be conducted for $F | nwt | C_{\max}$ and compared with the relaxed version of Model I. Afterwards, Model I, Model V and Model VI will be considered for further numerical experiments of $F | nwt, d_j | C_{\max}$.

Table 1 presents the numerical results of the following models: original formulation of Model I when due date constraints are relaxed, Model I when equation (6) is replaced with indicator constraints and due date constraints are relaxed, and Model II when due date constraints are relaxed. In all of the following tables, OFV represents objective function value and all of the CPU times are reported in seconds. The time when the optimal solution was found is reported as well. For instance, according to Table 1 the optimal solution of *Sam04* is 9159; this solution has been found by the original formulation of Model I after 200 seconds. Moreover, numbers in boldface indicate that the reported solution is optimal. Therefore, NFS in boldface means that the problem has no feasible solutions; however, non-bold NFS means that although the algorithm has not been able find a feasible solution in the given time, the problem may or may not have feasible solutions.

Table 1 - Numerical results of $F | nwt | C_{\max}$

Problem	Size n*m	Model I - original formulation			Model I - indicator constraints			Model II		
		T=60	T=300	T=600	T=60	T=300	T=600	T=60	T=300	T=600
Sam01	7*7	7705, 1	7705, 1	7705, 1	7705, 39	7705, 39	7705, 39	7705, 1	7705, 1	7705, 1
Sam02	8*8	9372, 2	9372, 2	9372, 2	9372	9372	9372	9372, 1	9372, 1	9372, 1
Sam03	8*9	9690, 2	9690, 2	9690, 2	9690	9690	9690	9690, 1	9690, 1	9690, 1
Sam04	10*6	9159	9159, 200	9159, 200	9496	9159	9159	9159, 1	9159, 1	9159, 1
Sam05	11*5	8142	8142	8142	8246	8142	8142	8142, 2	8142, 2	8142, 2
Sam06	12*5	8923	8866	8866	9134	8884	8866	8866, 6	8866, 6	8866, 6
Sam07	13*4	8393	8242	8242	8728	8534	8299	8242, 1	8242, 1	8242, 1
Sam08	14*4	9412	9259	9195	9898	9562	9467	9195, 5	9195, 5	9195, 5
Sam09	15*6	13905	13704	13704	NFS	NFS	NFS	13330	13330	13330
Sam10	16*7	9057	9057	9057	NFS	9177	9129	8869	8869	8869
Sam11	17*5	11679	11467	11359	NFS	12365	11903	10950	10950	10950
Sam12	18*9	9546	9541	9541	NFS	NFS	NFS	8824	8824	8824
Sam13	19*8	18676	18574	18143	NFS	NFS	NFS	17428	17428	17428
Sam14	20*10	34015	33449	31370	37575	37575	37575	29318	29318	29318
Optimality proved		21.43%	28.57%	28.57%	7.14%	7.14%	7.14%	57.14%	57.14%	57.14%

It can be noted that the CPU times of Model II were under 10 seconds for problems *Sam01* through *Sam08*; the CPU time jumps to 808 seconds to solve *Sam09* to optimality. Accordingly, computational results for problems *Sam01* through *Sam08* and *Sam09* through *Sam14* will be presented in separate tables hereinafter. Note that none of the models were able to find an optimal solution for the problems with more than 16 jobs. On the other hand, the original formulation of Model I did not fathom all the nodes to prove the optimality of the proposed solutions in less than 300 seconds once the problem instance consisted of more than 10 jobs. As mentioned before, employing indicator constraints reduces the branching efficiency of CPLEX. Table 1 shows that Model I with indicator constraints is the least competitive model and is able to prove the optimality of only one of the test cases. This table is another pointer for the competitiveness of Model II; as mentioned before, solving $F | nwt, d_j | C_{\max}$ using Model II can be considered as an interesting future research.

Table 2 summarizes the numerical results of Model I with the original formulation of section 3.1 as well as when equation (6) is replaced with indicator constraints. Superiority of the original formulation of Model I over the indicator constraints formulation is evident from this table. Therefore, only the results of the original formulation of Model I will be reported for $T = 7200$. Both of these formulations proved to be most effective for the test problems with less than 12 jobs. Moreover, the original formulation of Model I has found the optimal solution of 44.64% of the test problems in $T = 7200$ in Table 2.

Table 2 – Computational results of Model I

Problem	Size n*m	Due date TF	Original formulation - OFV				Indicator constraints - OFV		
			T=60	T=300	T=600	T=7200	T=60	T=300	T=600
Sam01+DD	7*7	TF=1	7705, 2	7705, 2	7705, 2	7705, 2	7705, 20	7705, 20	7705, 20
		TF=2	7705, 2	7705, 2	7705, 2	7705, 2	7705, 9	7705, 9	7705, 9
		TF=3	7705, 2	7705, 2	7705, 2	7705, 2	7705, 2	7705, 2	7705, 2
		TF=4	NFS, 14	NFS, 14	NFS, 14	NFS, 14	NFS, 54	NFS, 54	NFS, 54
Sam02+DD	8*8	TF=1	9372, 11	9372, 11	9372, 11	9372, 11	9485	9448	9372
		TF=2	9372, 11	9372, 11	9372, 11	9372, 11	9372	9372, 205	9372, 205
		TF=3	9573, 11	9573, 11	9573, 11	9573, 11	9573, 51	9573, 51	9573, 51
		TF=4	NFS, 12	NFS, 12	NFS, 12	NFS, 12	NFS, 48	NFS, 48	NFS, 48
Sam03+DD	8*9	TF=1	9690, 10	9690, 10	9690, 10	9690, 10	9690	9690	9690
		TF=2	9690, 10	9690, 10	9690, 10	9690, 10	9874	9690, 183	9690, 183
		TF=3	9690, 10	9690, 10	9690, 10	9690, 10	9690, 50	9690, 50	9690, 50
		TF=4	NFS	NFS, 290	NFS, 290	NFS, 290	NFS	NFS	NFS
Sam04+DD	10*6	TF=1	9159	9159	9159, 334	9159, 334	9188	9159	9159
		TF=2	9483	9454, 224	9454, 224	9454, 224	9817	9454	9454
		TF=3	NFS	11537, 174	11537, 174	11537, 174	NFS	11537, 254	11537, 254
		TF=4	NFS, 25	NFS, 25	NFS, 25	NFS, 25	NFS	NFS, 132	NFS, 132
Sam05+DD	11*5	TF=1	8152	8152	8152	8152, 3966	8164	8164	8164
		TF=2	8381	8381	8168	8164, 3402	8284	8284	8164
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 4	NFS, 4	NFS, 4	NFS, 4	NFS	NFS, 62	NFS, 62
Sam06+DD	12*5	TF=1	9273	9170	9102	9084	9219	9219	9219
		TF=2	9339	9148	9120	9120	9980	9236	9226
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS, 305	NFS, 305	NFS	NFS	NFS
Sam07+DD	13*4	TF=1	8496	8496	8476	8465	9297	8895	8476
		TF=2	NFS	NFS	9139	9002	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS, 298	NFS, 298	NFS, 298	NFS	NFS	NFS, 330
Sam08+DD	14*4	TF=1	9802	9721	9674	9674	10845	10856	10266
		TF=2	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 4	NFS, 4	NFS, 4	NFS, 4	NFS	NFS	NFS
Sam09+DD	15*6	TF=1	14260	14260	14260	13472	NFS	NFS	NFS
		TF=2	NFS	NFS	NFS	14666	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 3	NFS, 3	NFS, 3	NFS, 3	NFS	NFS	NFS
Sam10+DD	16*7	TF=1	9201	9192	9192	9017	9678	9544	9420
		TF=2	9188	9113	9113	8977	9163	9136	9136
		TF=3	NFS	NFS	NFS	9262	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam11+DD	17*5	TF=1	12246	12246	12162	11371	NFS	NFS	NFS
		TF=2	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 2	NFS, 2	NFS, 2	NFS, 2	NFS	NFS	NFS
Sam12+DD	18*9	TF=1	9360	9360	9360	8904	10441	9736	9736
		TF=2	10172	9680	9600	9232	NFS	10338	10215
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 54	NFS, 54	NFS, 54	NFS, 54	NFS	NFS	NFS
Sam13+DD	19*8	TF=1	19361	19006	19006	17970	NFS	NFS	NFS
		TF=2	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam14+DD	20*10	TF=1	33602	33602	32626	31199	NFS	NFS	NFS
		TF=2	NFS	NFS	NFS	34399	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Percent of efforts with optimum solution			32.14%	37.50%	41.07%	44.64%	12.50%	21.43%	23.21%

Table 3 – Computational results of Model V and Model VI

Problem	Size n*m	Due date TF	Best solution from Table 2	Model V - OFV				Model VI		
				T=60	T=300	T=600	T=7200	T=60	T=300	T=600
Sam01+DD	7*7	TF=1	7705, 2	7705, 1	7705, 1	7705, 1	7705, 1	7705, 42	7705, 42	7705, 42
		TF=2	7705, 2	7705, 1	7705, 1	7705, 1	7705, 1	7705, 40	7705, 40	7705, 40
		TF=3	7705, 2	7705, 1	7705, 1	7705, 1	7705, 1	7705, 19	7705, 19	7705, 19
		TF=4	NFS, 14	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1
Sam02+DD	8*8	TF=1	9372, 11	9372, 22	9372, 22	9372, 22	9372, 22	9372	9372	9372
		TF=2	9372, 11	9372, 16	9372, 16	9372, 16	9372, 16	9372	9372	9372
		TF=3	9573, 11	9573, 25	9573, 25	9573, 25	9573, 25	9573	9573	9573
		TF=4	NFS, 12	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 8	NFS, 8	NFS, 8
Sam03+DD	8*9	TF=1	9690, 10	9690, 9	9690, 9	9690, 9	9690, 9	9690	9690	9690
		TF=2	9690, 10	9690, 10	9690, 10	9690, 10	9690, 10	10399	9690	9690
		TF=3	9690, 10	9690, 5	9690, 5	9690, 5	9690, 5	10229	9874	9690
		TF=4	NFS, 290	NFS, 4	NFS, 4	NFS, 4	NFS, 4	NFS, 15	NFS, 15	NFS, 15
Sam04+DD	10*6	TF=1	9159, 334	9332	9159	9159	9159, 1264	9959	9623	9423
		TF=2	9454, 224	9454	9454	9454	9454, 682	10251	10251	9558
		TF=3	11537, 174	11537	11537	11537	11537, 504	NFS	NFS	NFS
		TF=4	NFS, 25	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 4	NFS, 4	NFS, 4
Sam05+DD	11*5	TF=1	8152, 3966	8211	8211	8152	8152	8723	8652	8336
		TF=2	8164, 3402	8164	8164	8164	8164	9287	9261	8284
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 4	NFS, 2	NFS, 2	NFS, 2	NFS, 2	NFS, 2	NFS, 2	NFS, 2
Sam06+DD	12*5	TF=1	9084	9091	9091	9091	9084	9972	9972	9733
		TF=2	9120	9148	9148	9120	9120	10197	9877	9662
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 305	NFS, 9	NFS, 9	NFS, 9	NFS, 9	NFS, 13	NFS, 13	NFS, 13
Sam07+DD	13*4	TF=1	8465	8471	8471	8465	8465	10488	9829	8818
		TF=2	9002	9175	9002	9002	9002	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 298	NFS	NFS, 210	NFS, 210	NFS, 210	NFS, 24	NFS, 24	NFS, 24
Sam08+DD	14*4	TF=1	9674	10494	10290	9798	9746	12219	12114	11309
		TF=2	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 4	NFS	NFS	NFS, 570	NFS, 570	NFS	NFS	NFS
Sam09+DD	15*6	TF=1	13472	14226	14001	14001	13491	17033	16324	16324
		TF=2	14666	13706	13583	13583	13330	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 3	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam10+DD	16*7	TF=1	9017	9013	9011	9011	8912	9740	9552	9509
		TF=2	8977	9210	9030	9030	8975	10104	9566	9489
		TF=3	9262	9334	9223	9221	9116	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam11+DD	17*5	TF=1	11371	11639	11530	11530	11268	14127	12641	12641
		TF=2	NFS	NFS	NFS	12243	11576	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 2	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam12+DD	18*9	TF=1	8904	9174	9036	9036	8902	10883	10463	10463
		TF=2	9232	9695	9568	9485	9304	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS, 54	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam13+DD	19*8	TF=1	17970	18621	18621	18621	17996	NFS	NFS	NFS
		TF=2	NFS	NFS	19954	19373	18453	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Sam14+DD	20*10	TF=1	31199	32949	32949	32635	30822	NFS	38299	38299
		TF=2	34399	NFS	32511	32511	30715	NFS	NFS	NFS
		TF=3	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
		TF=4	NFS	NFS	NFS	NFS	NFS	NFS	NFS	NFS
Percent of efforts with optimum solution			44.64%	26.79%	28.57%	30.36%	35.71%	17.86%	17.86%	17.86%

Table 4 – Computational results of The Enumeration Algorithms

Problem	Size n*m	Due date TF	Algorithm 2 - OFV				Algorithm 1 - OFV		
			T=60	T=300	T=600	T=7200	T=60	T=300	T=600
Sam01+DD	7*7	TF=1	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0
		TF=2	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0
		TF=3	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0	7705, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam02+DD	8*8	TF=1	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0
		TF=2	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0	9372, 0
		TF=3	9573, 0	9573, 0	9573, 0	9573, 0	9573, 0	9573, 0	9573, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam03+DD	8*9	TF=1	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0
		TF=2	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0
		TF=3	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0	9690, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam04+DD	10*6	TF=1	9159, 0	9159, 0	9159, 0	9159, 0	9159, 2	9159, 2	9159, 2
		TF=2	9454, 0	9454, 0	9454, 0	9454, 0	9454, 0	9454, 0	9454, 0
		TF=3	11537, 0	11537, 0	11537, 0	11537, 0	11537, 0	11537, 0	11537, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam05+DD	11*5	TF=1	8152, 2	8152, 2	8152, 2	8152, 2	8152, 17	8152, 17	8152, 17
		TF=2	8164, 1	8164, 1	8164, 1	8164, 1	8164, 9	8164, 9	8164, 9
		TF=3	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam06+DD	12*5	TF=1	9084, 9	9084, 9	9084, 9	9084, 9	9084, 54	9084, 54	9084, 54
		TF=2	9120, 2	9120, 2	9120, 2	9120, 2	9120, 25	9120, 25	9120, 25
		TF=3	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam07+DD	13*4	TF=1	8465, 11	8465, 11	8465, 11	8465, 11	9002	8465, 226	8465, 226
		TF=2	9002, 1	9002, 1	9002, 1	9002, 1	9002, 11	9002, 11	9002, 11
		TF=3	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam08+DD	14*4	TF=1	9674, 59	9674, 59	9674, 59	9674, 59	10613	9699	9699
		TF=2	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 24	NFS, 24	NFS, 24
		TF=3	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 6	NFS, 6	NFS, 6
		TF=4	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0	NFS, 0
Sam09+DD	15*6	TF=1	14976	14386	14136	14136	15999	14991	14976
		TF=2	13636	13330, 103	13330, 103	13330, 103	15809	15014	14031
		TF=3	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 59	NFS, 59	NFS, 59
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1
Sam10+DD	16*7	TF=1	9419	9419	9402	9364	9419	9419	9402
		TF=2	9445	9402	9402	9402	9451	9432	9402
		TF=3	9265	9142	9057	9057, 716	NFS	9374	9374
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 11	NFS, 11	NFS, 11
Sam11+DD	17*5	TF=1	12077	11829	11829	11829	12680	12627	12625
		TF=2	12503	11571	11534	11534, 860	NFS	NFS	NFS
		TF=3	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS	NFS, 137	NFS, 137
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 1
Sam12+DD	18*9	TF=1	10913	10813	10432	10432	10980	10886	10813
		TF=2	10615	10363	10363	10349	11199	10943	10943
		TF=3	NFS	NFS	9663	9663	NFS	NFS	NFS
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 2	NFS, 2	NFS, 2
Sam13+DD	19*8	TF=1	20699	20589	20497	20321	21204	21108	21023
		TF=2	20243	20119	19944	19849	NFS	NFS	NFS
		TF=3	NFS, 42	NFS, 42	NFS, 42	NFS, 42	NFS	NFS	NFS
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 2	NFS, 2	NFS, 2
Sam14+DD	20*10	TF=1	35847	35847	35847	35847	37045	36754	36754
		TF=2	34575	34430	33349	33065	NFS	NFS	NFS
		TF=3	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS	NFS	NFS
		TF=4	NFS, 1	NFS, 1	NFS, 1	NFS, 1	NFS, 17	NFS, 17	NFS, 17
Percent of efforts with optimum solution			75.00%	76.79%	76.79%	80.36%	66.07%	69.64%	69.64%

Table 5 – Overall comparison of the computational results at $T = 7200$

Problem	Size n*m	Due date TF	Model I – original Formulation	Model V	Algorithm 2
Sam01+DD	7*7	TF=1	7705, 2	7705, 1	7705, 0
		TF=2	7705, 2	7705, 1	7705, 0
		TF=3	7705, 2	7705, 1	7705, 0
		TF=4	NFS, 14	NFS, 1	NFS, 0
Sam02+DD	8*8	TF=1	9372, 11	9372, 22	9372, 0
		TF=2	9372, 11	9372, 16	9372, 0
		TF=3	9573, 11	9573, 25	9573, 0
		TF=4	NFS, 12	NFS, 1	NFS, 0
Sam03+DD	8*9	TF=1	9690, 10	9690, 9	9690, 0
		TF=2	9690, 10	9690, 10	9690, 0
		TF=3	9690, 10	9690, 5	9690, 0
		TF=4	NFS, 290	NFS, 4	NFS, 0
Sam04+DD	10*6	TF=1	9159, 334	9159, 1264	9159, 0
		TF=2	9454, 224	9454, 682	9454, 0
		TF=3	11537, 174	11537, 504	11537, 0
		TF=4	NFS, 25	NFS, 1	NFS, 0
Sam05+DD	11*5	TF=1	8152, 3966	8152	8152, 2
		TF=2	8164, 3402	8164	8164, 1
		TF=3	NFS	NFS	NFS, 0
		TF=4	NFS, 4	NFS, 2	NFS, 0
Sam06+DD	12*5	TF=1	9084	9084	9084, 9
		TF=2	9120	9120	9120, 2
		TF=3	NFS	NFS	NFS, 0
		TF=4	NFS, 305	NFS, 9	NFS, 0
Sam07+DD	13*4	TF=1	8465	8465	8465, 11
		TF=2	9002	9002	9002, 1
		TF=3	NFS	NFS	NFS, 0
		TF=4	NFS, 298	NFS, 210	NFS, 0
Sam08+DD	14*4	TF=1	9674	9746	9674, 59
		TF=2	NFS	NFS	NFS, 1
		TF=3	NFS	NFS	NFS, 0
		TF=4	NFS, 4	NFS, 570	NFS, 0
Sam09+DD	15*6	TF=1	13472	13491	14136
		TF=2	14666	13330	13330, 103
		TF=3	NFS	NFS	NFS, 1
		TF=4	NFS, 3	NFS	NFS, 1
Sam10+DD	16*7	TF=1	9017	8912	9364
		TF=2	8977	8975	9402
		TF=3	9262	9116	9057, 716
		TF=4	NFS	NFS	NFS, 1
Sam11+DD	17*5	TF=1	11371	11268	11829
		TF=2	NFS	11576	11534, 860
		TF=3	NFS	NFS	NFS, 1
		TF=4	NFS, 2	NFS	NFS, 1
Sam12+DD	18*9	TF=1	8904	8902	10432
		TF=2	9232	9304	10349
		TF=3	NFS	NFS	9663
		TF=4	NFS, 54	NFS	NFS, 1
Sam13+DD	19*8	TF=1	17970	17996	20321
		TF=2	NFS	18453	19849
		TF=3	NFS	NFS	NFS, 42
		TF=4	NFS	NFS	NFS, 1
Sam14+DD	20*10	TF=1	31199	30822	35847
		TF=2	34399	30715	33065
		TF=3	NFS	NFS	NFS, 1
		TF=4	NFS	NFS	NFS, 1
Percent of efforts with optimum solution			44.64%	35.71%	80.36%

Table 3 summarizes the results of Model V and Model VI. In this table only the results of Model V will be reported for $T = 7200$ due to its numerical supremacy over Model VI. A comparison between Table 2, and Table 3 reveals the superiority of the original formulation of Model I over the rest of the formulations. Computational results of the enumeration algorithms are presented in Table 4. In this table only the results of Algorithm 2 will be reported for $T = 7200$ due to its numerical supremacy over Algorithm 1. According to Table 4, Algorithm 2 finds the optimal solution of the test problems Sam01+DD through Sam08+DD in under 60 seconds. Overall, this algorithm finds the optimal solution of 80.36% of the test problems at $T = 7200$, which is superior to all of the mathematical and constraint programming models studied in this paper.

A closer comparison between Algorithm 2, Model V, and Model I with the original formulation is presented in Table 5. All of results in this table are for $T = 7200$. Computational supremacy of Algorithm 2 over the competitive methods is evident from this table. Algorithm 2 not only finds the optimal solution of 80.36% of the test problems, it is also able to find at least one feasible solution for one of the test problems (*Sam12+DD* with tightness factor 3) for which Model I and Model V have returned no feasible solutions in $T = 7200$.

6. Conclusions

The no-wait flow shop problem with due date constraints and makespan criterion has been considered in this paper. The problem is strongly NP-hard. Six mathematical models have been developed for the problem; namely, a mixed integer programming model, three quadratic mixed integer programming formulations, and two constraint programming models. Some of these models work based on the definition of contribution of a job to the makespan; an efficient algorithm has been proposed to calculate such contributions. Furthermore, a graph modelling of the problem as well as an exact enumeration algorithm that employed such modelling have been presented based on the definition of the contributions. A number of propositions have been proved to efficiently rule out infeasible solutions from the set of all possible permutations of $F | nwt, d_j | C_{\max}$. The results of these propositions were integrated into the enumeration algorithm. Moreover, solving complications as well as implementation difficulties have been discussed.

Finally, a thorough computational experiment has been conducted to compare the performance of the developed models and the enumeration algorithm. Computational results illustrate that as the problem size grows, finding a feasible solution for $F | nwt, d_j | C_{\max}$ is not an easy task. Numerical results reveal that the enumeration algorithm outperforms the other formulations when implemented by IBM ILOG CPLEX.

Finally, developing tight lower and upper bounds for $F | nwt, d_j | C_{\max}$ is an interesting future research direction. Moreover, solving quadratic programming models using semi-definite programming techniques, if possible, is very promising.

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